

WHAT IS LAPDOG™?

"Our goal is to have your DOG be on your LAP (LapDog) the same day after their surgery."

- Top-notch pet care for all shapes and sizes
- Exclusive access to LiftLoop[™] device
- Collaboration with world-class laparoscopy experts
- Primary revenue from the DogHouse[™]
 Repurchase of disposable components/replacement parts



OUR TEAM





George Fairchild

Ryan Buchanan







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Jordan Rhymer

Jackson Sammartino

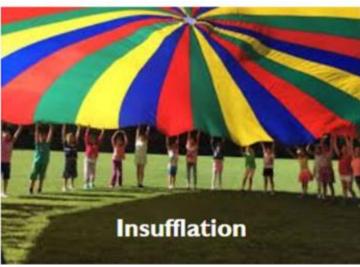


Raymond Millero

Max Usher



PROBLEM





Harrison, Case, et al. 2024

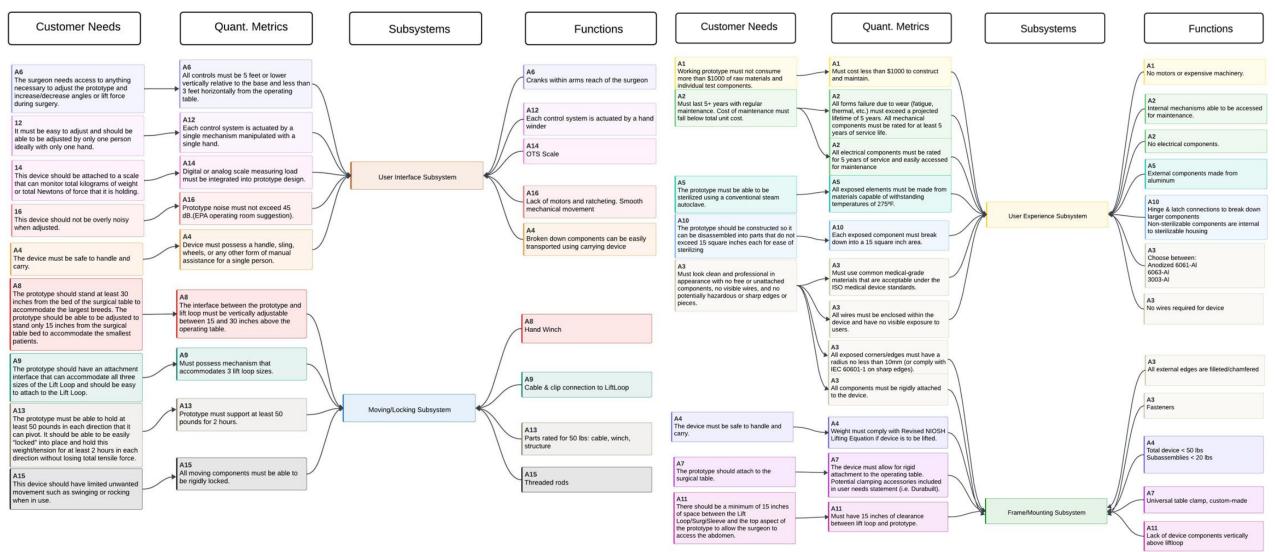
- Owners want health and safety for their pets
- High demand for minimally invasive methods • Less pain, less scarring, faster recovery
- A commercial device that utilizes lift laparoscopy rather than insufflation does not exist

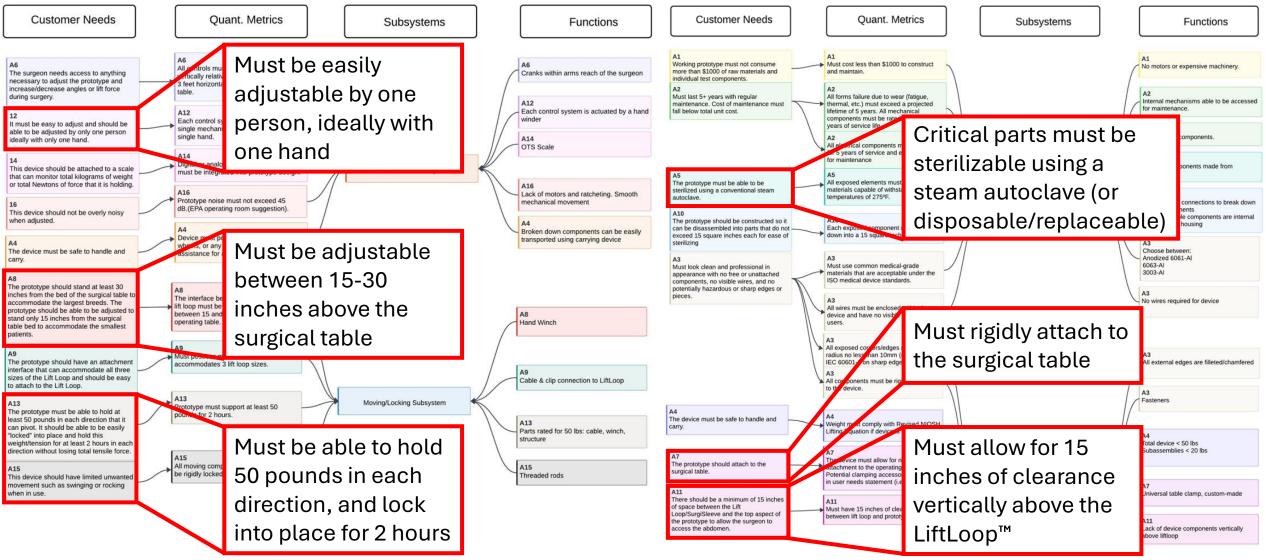
SOLUTION

• A reliable device that facilitates lift laparoscopy in the surgery of a dog or small animal, allowing vets to:

• Move & angle the patient in 6 degrees of freedom

- Support up to a **300-pound** patient
- Operate a rigidly attached device that is convenient and sterile

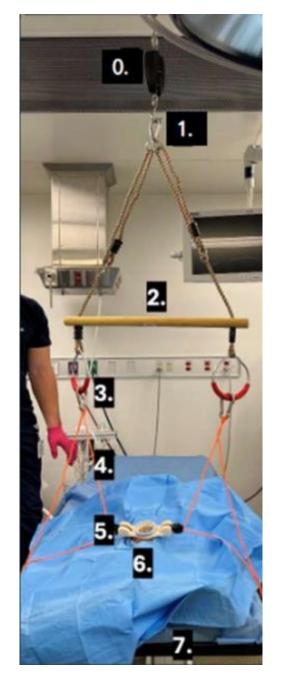




ORIGINAL DEVICE

- Starting point and proof of concept
- Areas for improvement:

 Unstable mounting/attachment
 Difficult to adjust
 1D motion only (up/down)
 - Materials difficult to sterilize



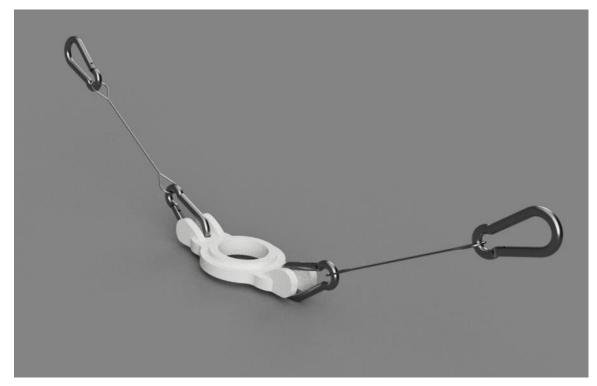
Harrison, Case, et al. 2024

NEW TECHNOLOGY

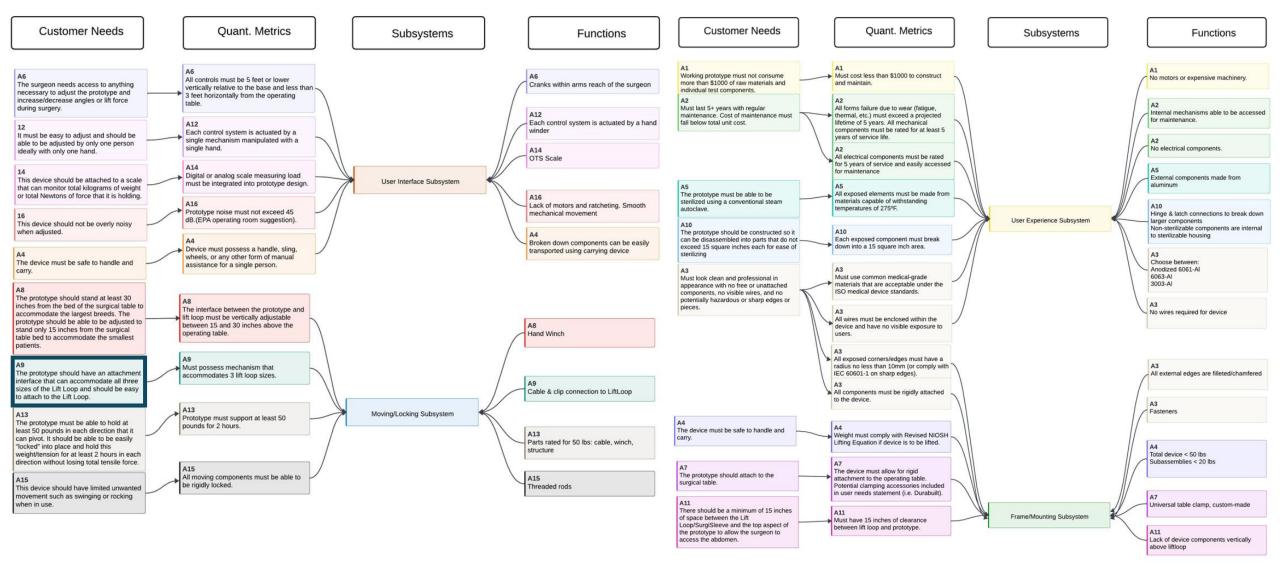
- LiftLoop™
- DogHouse™
- Rottwinder™
- Husky Handles[™] & Koolie Knobs[™]

LIFTLOOPTM

• Patented, custom 3D-printed device that allows vets to avoid gas insufflation completely, while still maintaining the benefits of MIS



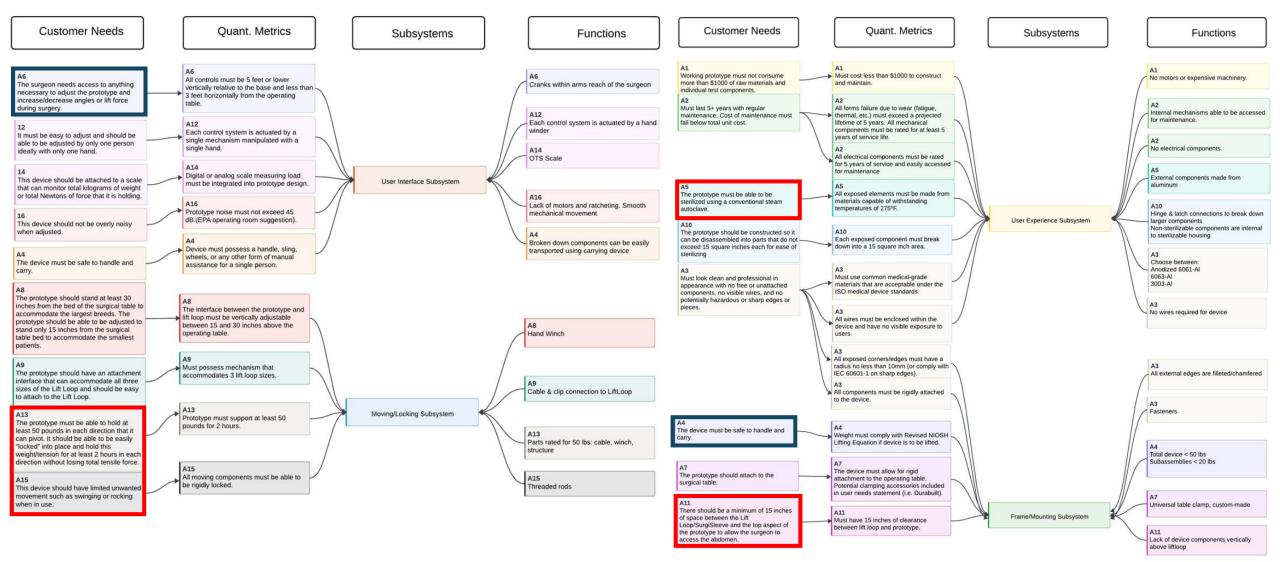
Harrison, Case, et al. 2024



THE DOGHOUSE™

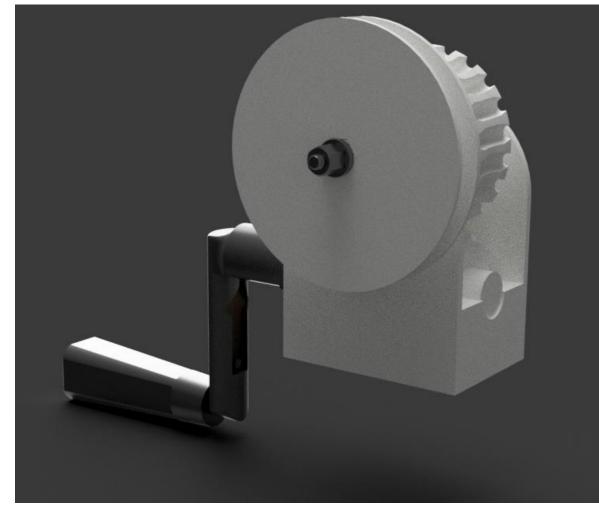
- Easy, rigid installation and use
- Motion in all directions
- All materials can be sterilized • Or reprinted/repurchased
- ~24.1 pounds

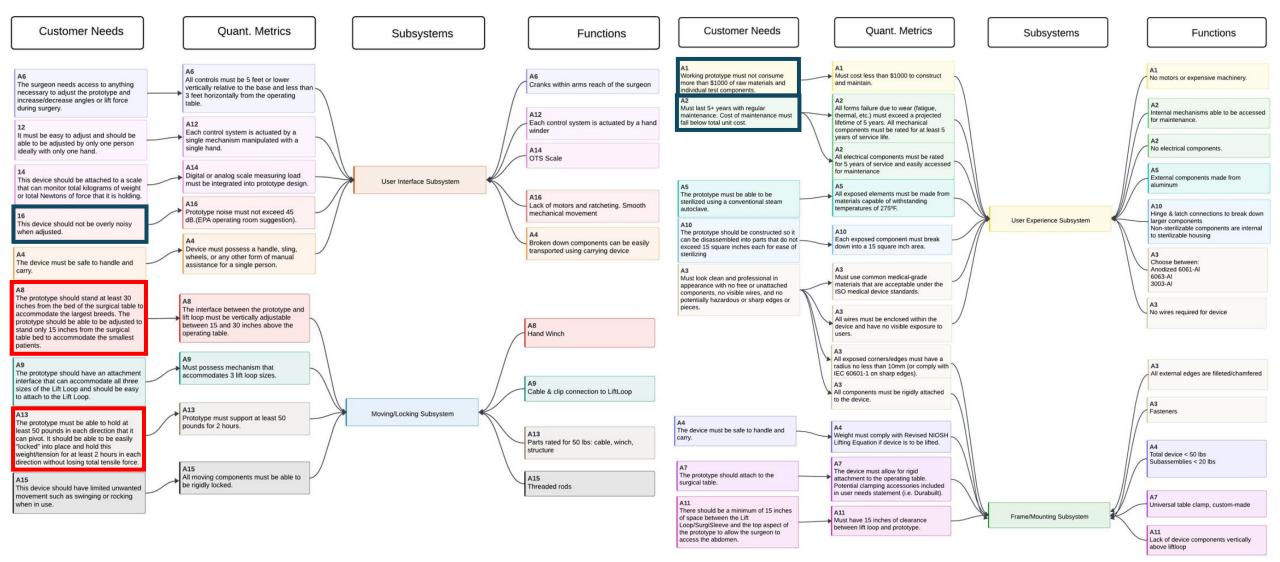




ROTTWINDERTM

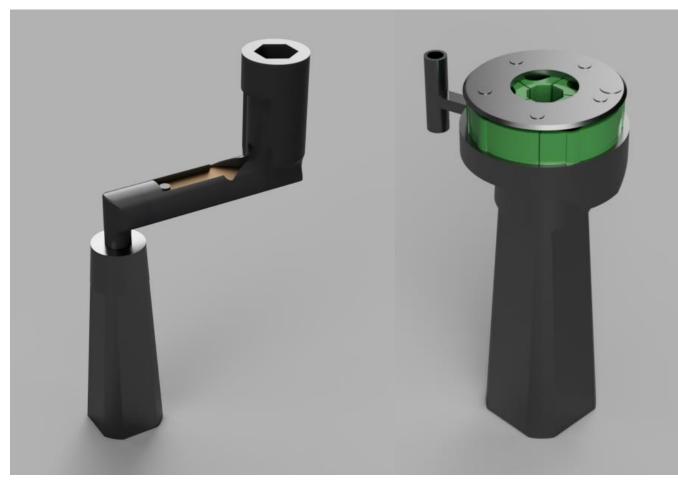
- 3D printable hand winch
- Durable, lightweight
- 22:1 worm gear ratio
- 0.47" linear spool per handle turn
- Self-locking





HUSKY HANDLES[™] & KOOLIE KNOBS[™]

- 3D-printable handles and knobs
- Large and ergonomic
- Easy to remove
- Maintains sterile environment
- Disposable/replaceable (secondary revenue)
- Rotating lockmechanism



Husky Handles ™ & Koolie Knobs ™ CAD Render

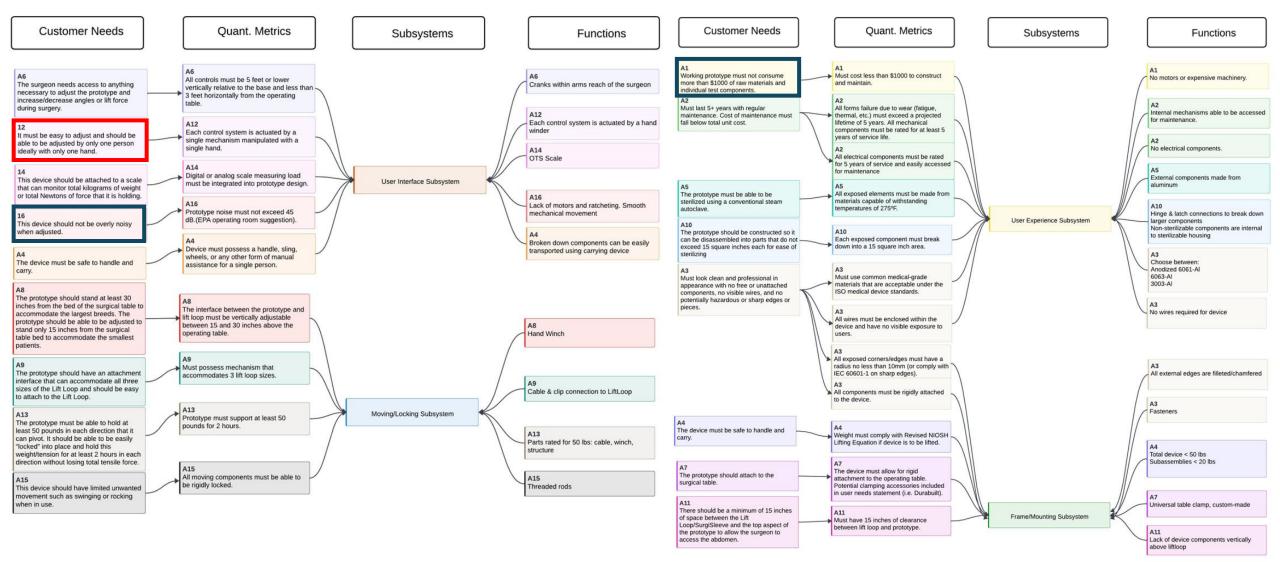
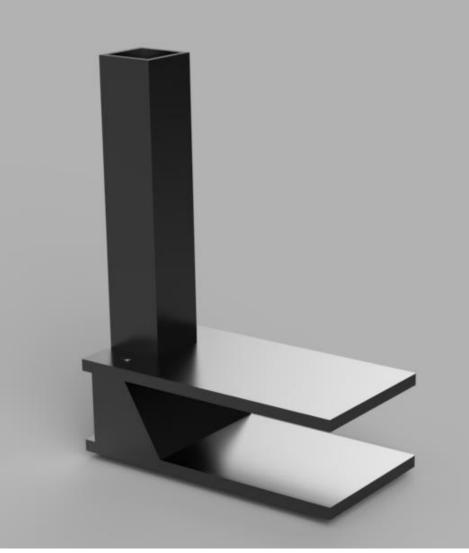
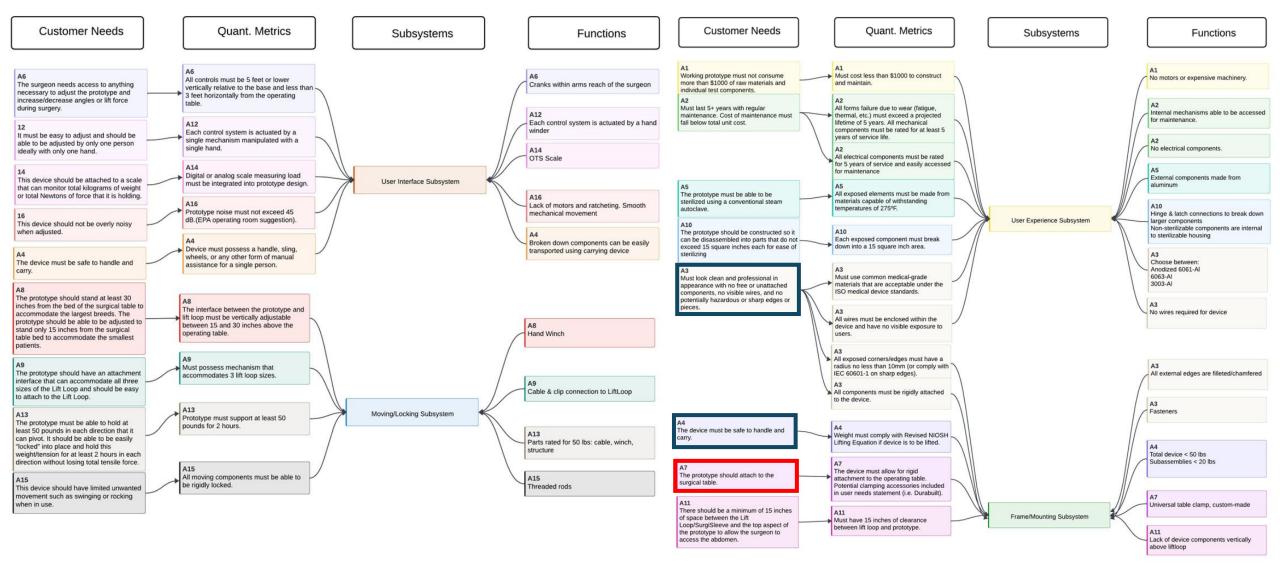


TABLE CLAMPS

- Easy to install with just 2 bolts/nuts each
- The DogHouse[™] fits in the square posts
- Allows for operation from side or bottom of table
- Large middle wedge prevents torsion of top/bottom plates
- ~3.5 pounds each

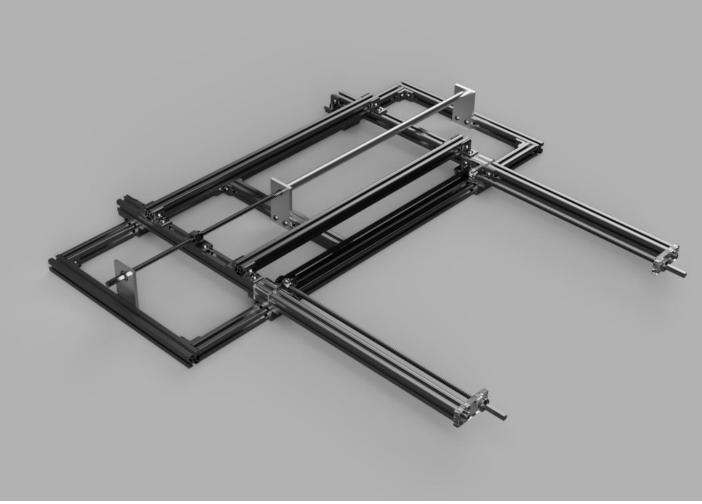


Clamps CAD Render

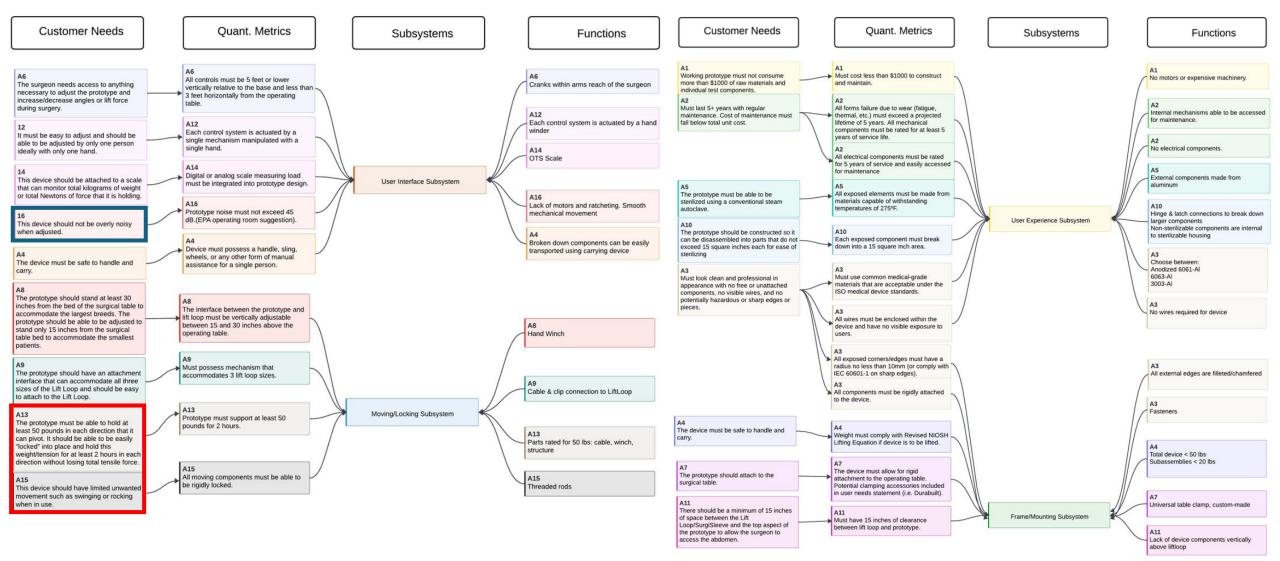


LINEAR MOTION

- Adjustable along both x and y axes
- Lead screws: ½" linear motion per turn
- Actuated by Husky Handles[™] and Koolie Knobs[™]
- Self-locking

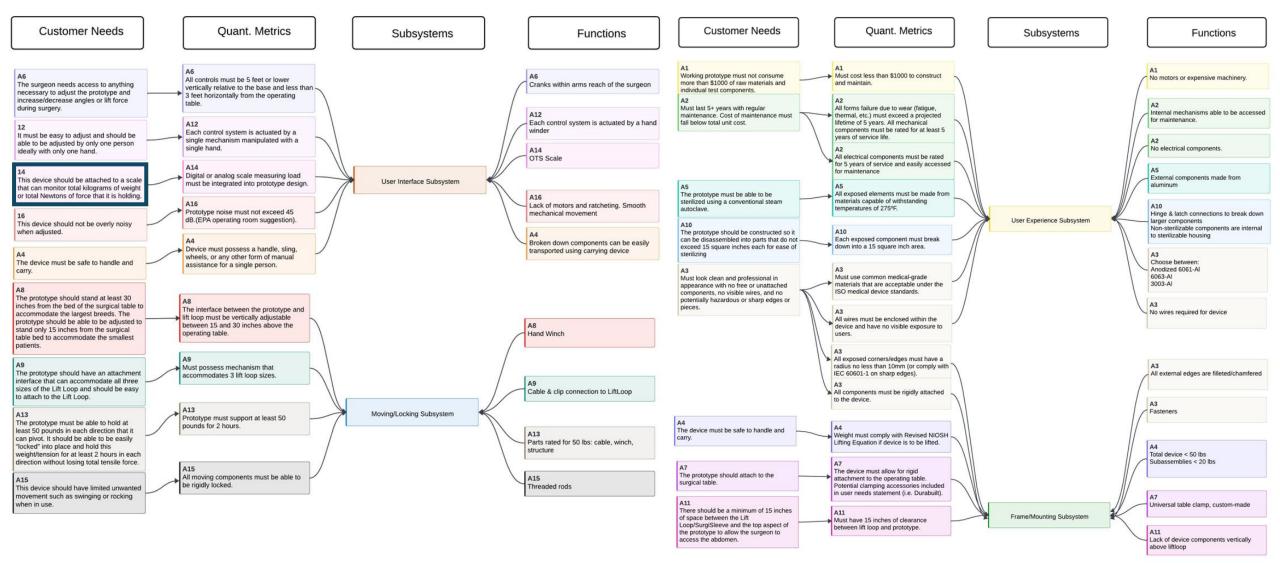


Upper DogHouse Frame CAD Render



INCORPORATING A SCALE

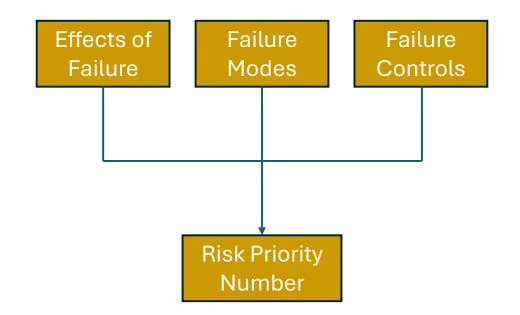




DESIGN SAFETY

- Design factor of safety chosen for:

 Consequences of catastrophic failure
 Uncertainty in materials
- FOS_d = 3.0
- Critical margins of safety (MOS) all positive
 - \odot Some too positive (optimization)
- Failure modes and effects analysis



CRITICAL COMPONENTS

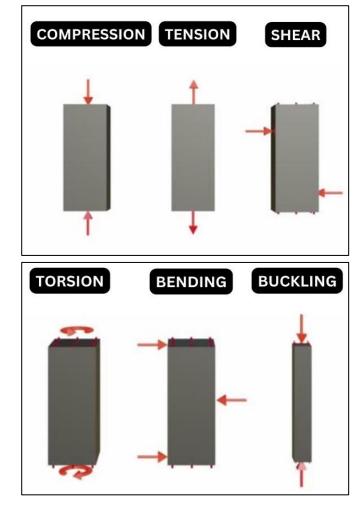
- 8020 branches
 - \odot Modeled as simply supported beams under bending and torsion
- Vertical 8020 members

Modeled as cantilever beams under bending
 Buckling

Clamps

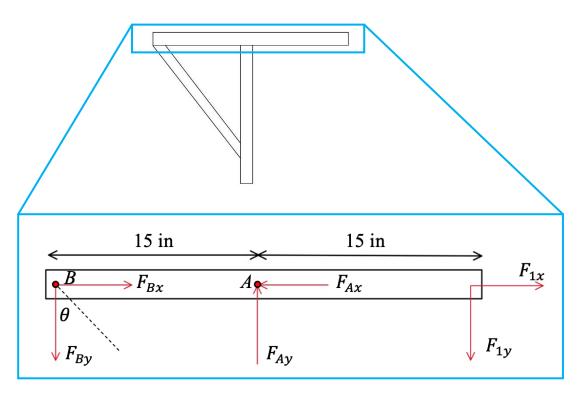
 \odot Cantilever beams under bending

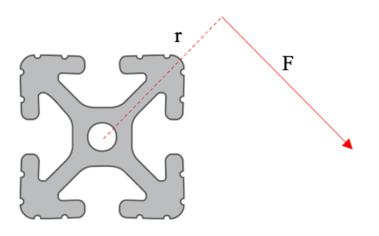
- Linear bearings
 - O Winch bearings under torsion
 O Frame bearings under vertical load



8020 BRANCHES

- Bending stress is most critical failure mode
- Shear stresses also a major concern
- Principal stresses calculated to apply failure criterion
- FOS_i: 3.1
- MOS: +0.02





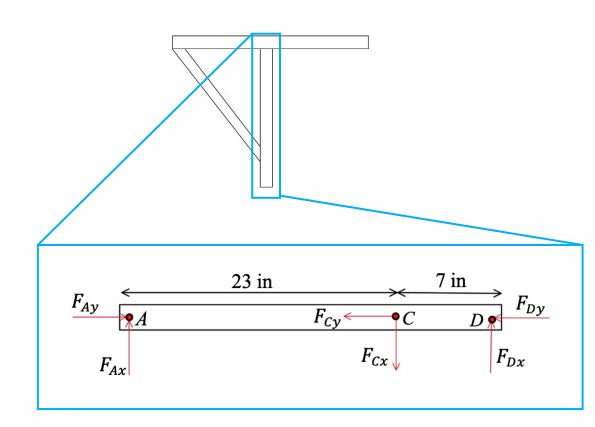
VERTICAL 8020

- Bending stress greatest at bottom
- Combined with compressive stress

 FOS_i: 4.1
 MOS: +0.36

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• Buckling not an issue $\circ F_{crit} = \sim 9,900 \text{ lbf}$



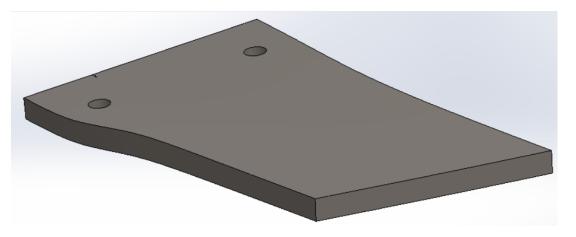
CLAMPS

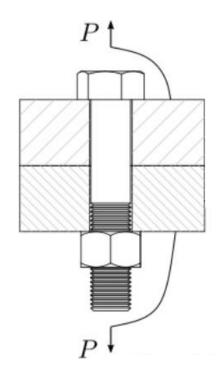
- Top plate bending along length and width

 FOS_i: 3.5
 MOS: +0.18
- 1/4" bolts under 550 lbf load

 Bolt preload found for joint separation FOS of 3.0
 Yield FOS_i: 2.8
 MOS: -0.06 ×
- 3/8" next nominal size

 FOS_i: 4.7
 MOS: +0.58



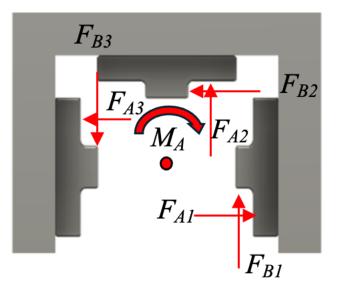


LINEAR BEARINGS

- Bearing pads most critical
- Shear forces generated by moment

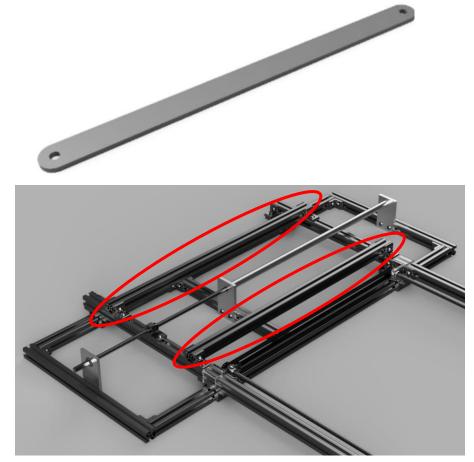
 FOS_i: 5.7
 MOS: +0.9
- Middle bearings under 100 lbf load • Recommended load capacity of 200 lbf





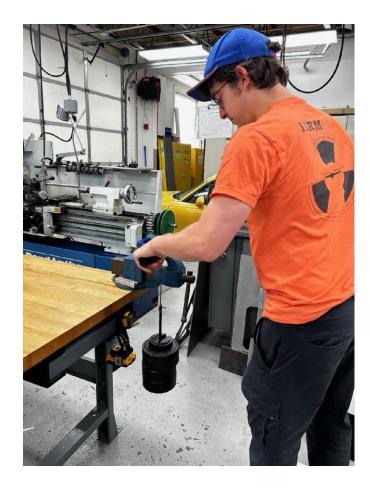
OVERDESIGN

- Diagonal members \circ MOS: +85
- Horizontal stiffeners \circ MOS: +250
- Goals:
 - Reduce weightMaintain stiffness





RottWinder[™] Hand Winch



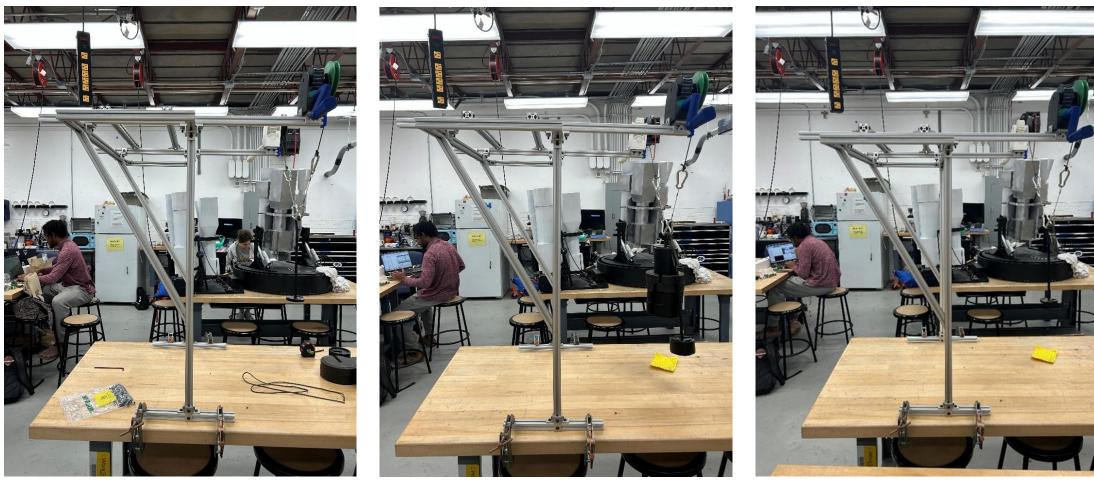
Category	Level 0	Level 1	Level 2	Level 3	Level 4
Vertical Range of Motion (20 pts)	Achieves less than 50% of the full range (0 pts).	Achieves at least 50% of the full range (5 pts).	Achieves at least 80% of the full range (10 pts).	Achieves full range of 15-30 inches (15 pts).	Exceeds range of 15-30 inches (20 pts).
Load Support (15 pts)	25 pounds causes winch to break (0 pts).	25 pounds causes winch to slip (5 pts).	Supports 25 pounds with large deformations (9 pts).	Supports 25 pounds with small deformations (12 pts).	Supports 25 pounds consistently with no complications) 15 pts).
Gear Ratio (10 pts)	Not functional or prohibitively slow (0 pts).	Functional but much lower than predicted gear ratio (4 pts).	Functional but slightly lower than predicted gear ratio (6 pts).	Matches predicted gear ratio (8 pts).	Exceeds predicted gear ratio (10 pts).
Rate of Travel (5 pts)	<0.5 inches per second (1 pts).	0.5+ inches per second (2 pts).	0.75+ inches per second (3 pts).	1+ inches per second (4 pts).	1.5+ inches per second (5 pts).

DogHouse[™] Frame





DogHouse[™] Frame



Before loading

During loading (~50 lbs)

After loading

DogHouse[™] Frame

Category	Level 0	Level 1	Level 2	Level 3	Level 4
Visual/Photographic Inspection (20 pts)	Broken components (0 pts).	Notable deformations (12 pts).	Minor deformations (15 pts).	Minor cosmetic damage (18 pts).	No visible damage or deformation (20 pts).
Structural Integrity (30 pts)	Frame does not remain functional (0 pts).	Frame remains functional with notable deformation (15 pts).	Frame remains functional with some deformation (20 pts).	Frame remains functional with low deformations (25 pts).	Frame remains fully functional and rigid (30 pts).

PERFORMANCE DEMONSTRATION





PERFORMANCE DEMONSTRATION

- Mounting and clamping demo
- Rottwinder[™] lifting demo



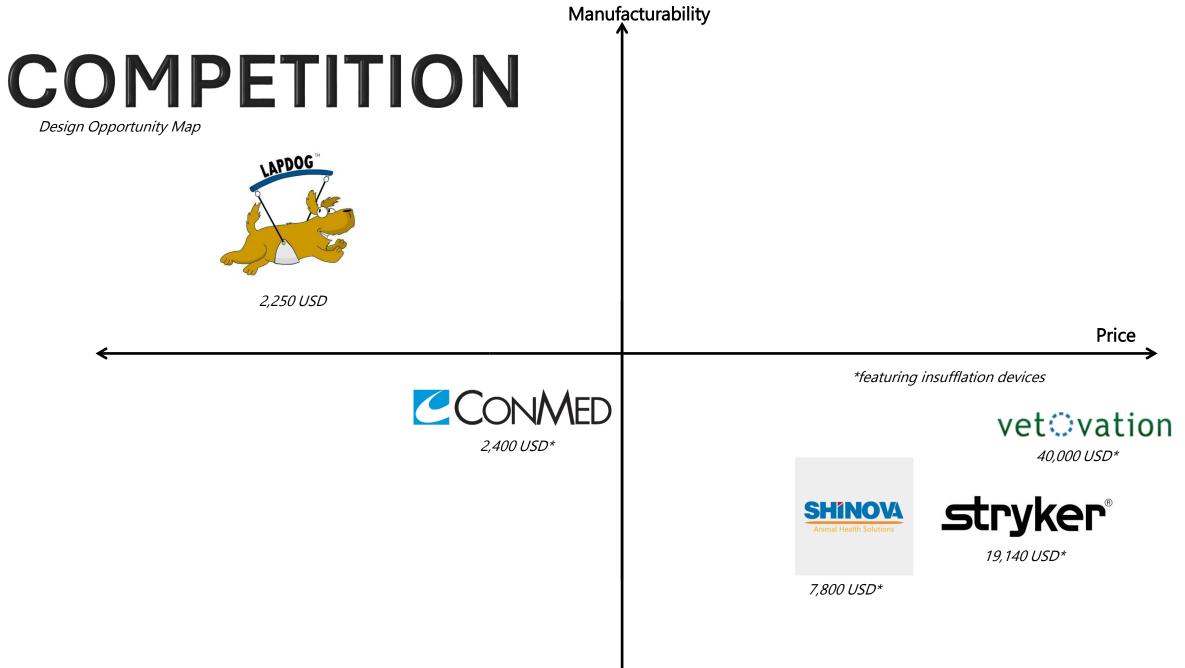


DESIGN IMPROVEMENTS

- Lower, more accessible handles
- Quicker, easier connection to LiftLoop[™]
- Faster winches/lead screws
- Make frame assembly easier
- Make table attachment (clamping) easier
- Foldable assembly
- Reduce material in overdesigned components
- Overall housing



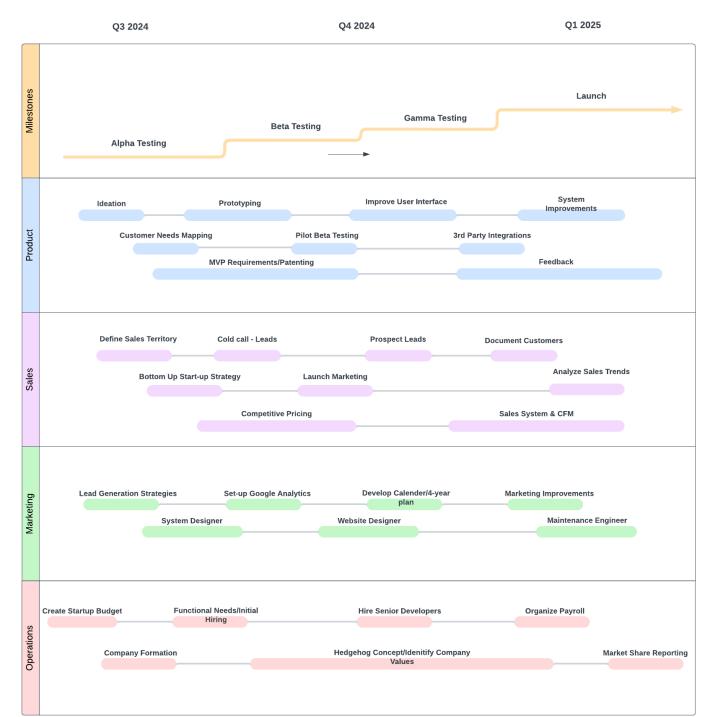
[https://filminflorida.com]



COMPETITIVE ADVANTAGES

- A blue ocean opportunity in lift laparoscopy
- Abdominal wall lifting is safer for use in small animals
 - Also is cheaper than insufflation
- Raw materials are under \$1,500

TRACTION



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FINANCIALS

Expense	Cost (\$)
Raw Material – Single Unit	1,426*
Raw Material – Batch Order (10 Units)	12,154*
3D Printers (20)	22,780
Mill/Lathe (2)	10,000
MIG Welder	1,000
Equipment Total	33,780
Single Unit Total	35,206
Batch Total	45,934

*40%-50% of raw material cost is associated with T slot linear bearings and corner brackets. We plan to 3D print the linear bearing housings in the future and can attempt to find a cheaper method of manufacturing the corner brackets ourselves, potentially reducing material cost drastically.

FINANCIALS



INVESTMENT

• Seeking \$150,000 investment

- Creating 10 DogHouse[™] units
- $_{\odot}$ Testing of these units in clinics around FL
- $_{\odot}$ Establishing a shop with 3D printers, mill, lathe, and MIG welder



